L Number	Hits	Search Text	DB	Time stamp
-	4	JP-07270137-$.did. JP-07319525-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/04/26 14:46
-	1	JP-04075887-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/04/26 14:55
-	2	WO-9942257-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/04/26 15:03
-	89	((382/153).CCLS.) and (inspect$3 or measur$3 or measurement)	USPAT; US-PGPUB	2004/04/26 16:16
-	113	(382/153).CCLS.	USPAT; US-PGPUB	2004/04/26 16:20
-	51	((382/153).CCLS.) and (learn$3 or teach$3 or registered or registering or registration)	USPAT; US-PGPUB	2004/04/26 16:26
-	7	arimatsu-taro.in.	USPAT; US-PGPUB	2004/04/26 16:40
-	2	JP-2000288968-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/04/26 16:39
-	2	EP-1043126-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/04/27 09:38
-	17	(382/$.ccls. 901/$.ccls.) and watanabe-atsushi.in.	USPAT; US-PGPUB	2004/04/26 16:41
-	54	watanabe-atsushi.in. and fanuc$.as.	USPAT; US-PGPUB	2004/04/26 16:43
-	197	(382/152).CCLS.	USPAT; US-PGPUB	2004/04/26 16:48
-	39	((382/152).CCLS.) and robot$3	USPAT; US-PGPUB	2004/04/26 16:55
-	67	((382/151).CCLS.) and robot$3	USPAT; US-PGPUB	2004/04/26 17:04
-	18	((plural$3 or multiple or dual or two or several or many) adj robot$3) same (video or camera or CCD or image or visual) same (workpiece or work-piece or (work adj part or piece) or model)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/04/26 17:07
-	138	((382/151-154).CCLS.) and (recogni$6 or identif$3 or identification) same robot$3	USPAT; US-PGPUB	2004/04/26 17:08
-	135	((plural$3 or multiple or dual or two or several or many) adj robot$3) and (video or camera or CCD or image or visual) same (workpiece or work-piece or (work adj part or piece) or modell$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/04/26 17:24
-	25	robot$3 same (camera or visual or CCD or optical) same (ax$s with rotat$3 with (perpendicular or orthogonal))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/04/26 17:37
-	17	((382/154).CCLS.) and (reference or register$3 or registration or teach$3 or train$3 or learn$3) with (object or model or part or workpiece or work-piece or work adj piece) same robot$3	USPAT; US-PGPUB	2004/04/26 17:38
-	60	901/47.ccls. and (workpiece or (work adj piece) or model or part) with (position or location) with (posture or orientation or arrangement)	USPAT; US-PGPUB	2004/04/26 17:38

-	25	901/47.ccls. and (plural$3 or multiple or several or many) with (video or camera or CCD or image or visual) same (workpiece or work-piece or (work adj part or piece) or model)	USPAT; US-PGPUB	2004/04/26 17:38
-	1	("5446835").PN.	USPAT; US-PGPUB	2004/04/26 17:39
-	275	(robot with (camera or CCD or image or visual)) same (robot with (workpiece or work-piece or (work adj part or piece) or model))	USPAT; US-PGPUB	2004/04/27 10:43
-	2	WO-9201539-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT	2004/04/27 09:38
-	17	("3576997" | "4459526" | "4707647" | "4725965" | "4731860" | "4831549" | "4843561" | "4985846" | "5083073" | "5297238" | "5446835" | "5467517" | "5523663" | "5552575" | "5680694" | "5903663" | "5968297").PN.	USPAT	2004/04/27 10:07
-	172	(382/$.ccls. 348/$.ccls. 356/$.ccls. 700/$.ccls. 901/$.ccls.) and robot$3 same (camera or CCD or imag$3 or video) same (position$3 or locat$4 or (three or "3") adj dimension$4 or 3D or 3-D or coordinate) with (orientation or posture or attitude or pose) with (object or workpiece or work adj piece or part or bin or pile$1 or article or body)	USPAT; US-PGPUB	2004/04/28 10:53
-	1	("4305130").PN.	USPAT; US-PGPUB	2004/04/27 11:24
-	162	(robot$3 or effector or manipulator) same (camera or CCD or imag$3 or video or visual) same (orientation or posture or attitude or pose or arrangement) same (compar$5 or correlat$4 or collat$4 or match$3 or correspond$4) with (model or stor$3 or taught or teaching or learn$3 or reference or registered or registration or recogni$6 or identif$4 or template or target)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/04/28 16:04
-	2	EP-1043689-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/04/28 12:44
-	2	WO-9724206-$.did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/04/28 16:04